

# lamaPLC: INA226 - current/voltage/power monitor with I<sup>2</sup>C communication



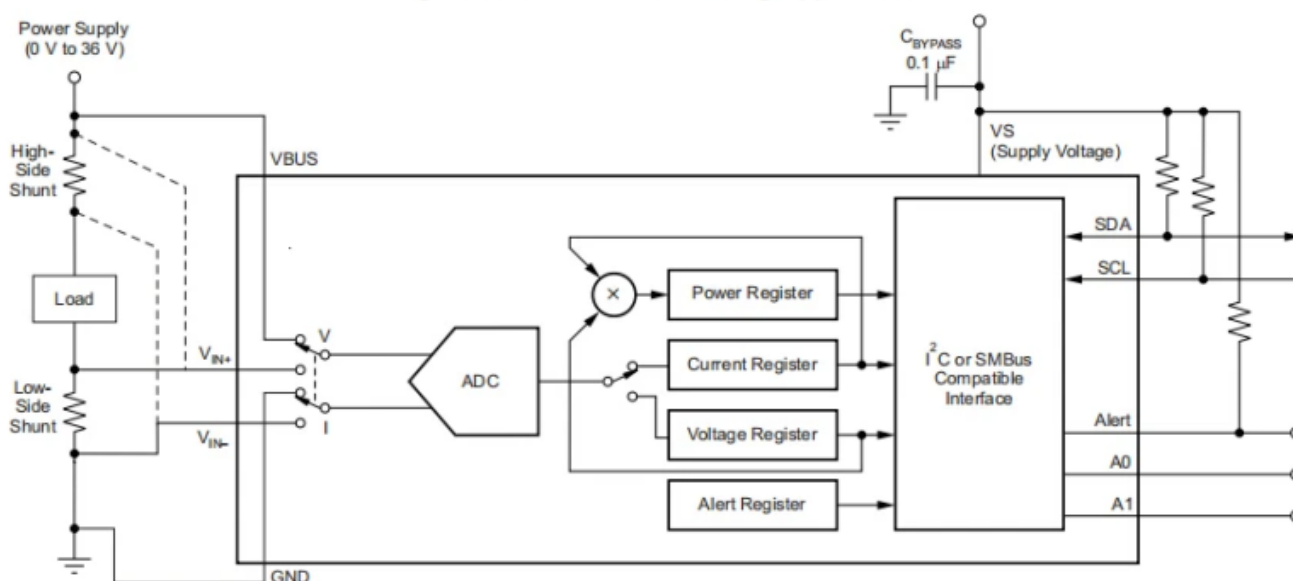
## 36V, 16-bit, ultra-precise i<sup>2</sup>c output current/voltage/power monitor w/alert

The INA226 is a current shunt and power monitor with an I<sup>2</sup>C or SMBUS-compatible interface. It monitors both a shunt voltage drop and bus supply voltage. Programmable calibration values, conversion times, and averaging, combined with an internal multiplier, enable direct readouts of current in amperes and power in watts.

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The INA226 supports the fast mode (1 kHz to 400 kHz) and high-speed mode (1 kHz to 2.94 MHz) transmission protocols. All data bytes are transmitted most significant byte first.

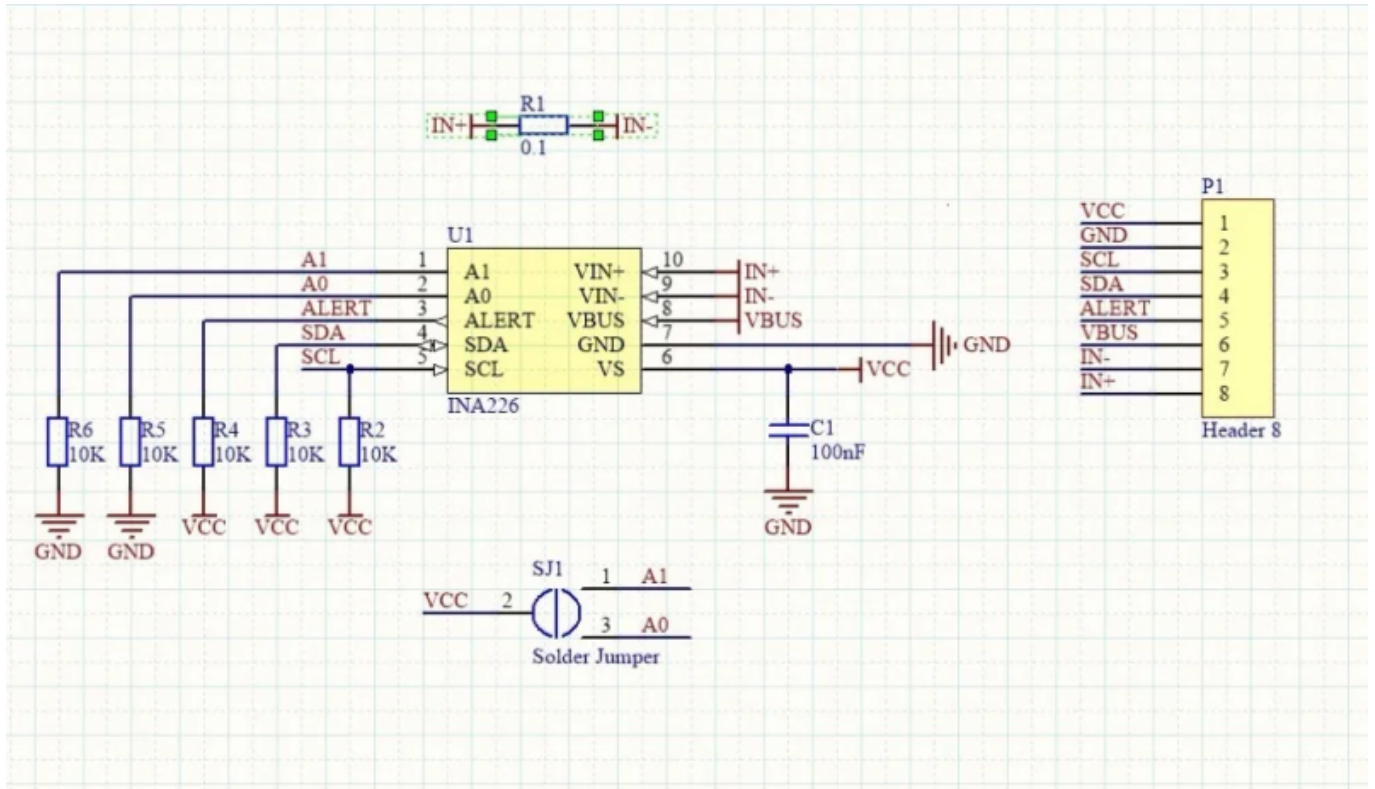
High-Side or Low-Side Sensing Application



coffee — or a few — [please do so here](#).

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## Features

- Senses Bus Voltages: 0 V .. 36 V
- Shunt Voltage Maximum: 81.9 V
- Current Maximum: 20 A
- High-Side or Low-Side Sensing
- Reports Current, Voltage, and Power
- High Accuracy:
  - 0.1% Gain Error (Max)
  - 10  $\mu$ V Offset (Max)
- Configurable Averaging Options
- 16 Programmable Addresses
- Operates from 2.7V to 5.5V Power Supply
- 10-Pin, DGS (VSSOP) Package

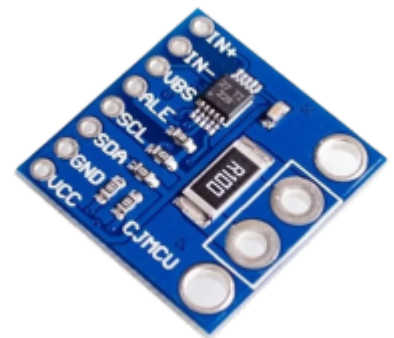
## Differences between the INA219 and INA226

The main differences between the **INA219** and **INA226** lie in their measurement resolution, voltage-handling capabilities, and advanced features. The INA226 is considered the "pro" version for more

demanding applications.

Feature	Texas Instruments INA219	Texas Instruments INA226
<b>ADC Resolution</b>	12-bit	16-bit (16x more precise)
<b>Max Bus Voltage</b>	26 V	36 V
<b>Shunt Voltage Range</b>	±320 mV	(with PGA) ±81.92 mV
<b>Programmable Gain Amplifier (PGA)</b>	Yes (2x, 4x, 8x gain options)	No
<b>Averaging Engine</b>	Configurable filtering options	Built-in "DSP" engine, up to 1024 samples
<b>Alert Pin</b>	Not explicitly mentioned as programmable	Programmable alert for overcurrent/voltage conditions
<b>Sensing Configuration</b>	High-side only	High-side or low-side
<b>Offset Voltage</b>	Max 100 µV	Max 10 µV

## Pin Description



Pin Name	Description
<b>V+ / VS</b>	<b>Power Supply:</b> 2.7V to 5.5V for the chip's own logic
<b>GND</b>	<b>Ground:</b> Reference point for power and I <sup>2</sup> C
<b>SCL</b>	<b>I<sup>2</sup>C Clock:</b> Connect to the microcontroller's SCL pin
<b>SDA</b>	<b>I<sup>2</sup>C Data:</b> Connect to the microcontroller's SDA pin
<b>VBUS</b>	<b>Bus Voltage Input:</b> Connect this to the high-side or load-side to measure the actual bus voltage (up to 36V)
<b>IN+</b>	<b>Shunt Positive:</b> Connect to the supply side of the external shunt resistor
<b>IN-</b>	<b>Shunt Negative:</b> Connect to the load side of the external shunt resistor
<b>A0 &amp; A1</b>	<b>Address Pins:</b> Used to set the I <sup>2</sup> C address by tying them to GND, VS, SDA, or SCL
<b>ALERT</b>	<b>Programmable Alert:</b> Open-drain output that can trigger on over/under voltage or current thresholds

## Typical Wiring (High-Side Sensing)

- **V+ and GND:** Connect to your microcontroller's 3.3V or 5V power and ground.
- **SDA and SCL:** Connect to your microcontroller's I<sup>2</sup>C pins.
- **IN+ and IN-:** Place the shunt resistor in series with your load's positive line. Connect IN+ before the resistor and IN- after it.
- **VBUS:** Connect this pin to IN- (load side) for standard high-side power monitoring.

## INA226 I2C Address Table

The Texas Instruments INA226 supports up to 16 unique I<sup>2</sup>C addresses. The address is set by connecting the two address pins (A0 and A1) to one of four possible points: GND, VS (power supply), SDA, or SCL.

The default address is **0x40** (when both pins are connected to GND).

A1 Pin	A0 Pin	Hex Address
<b>GND</b>	GND	<b>0x40</b>
<b>GND</b>	VS	0x41
<b>GND</b>	SDA	0x42
<b>GND</b>	SCL	0x43
<b>VS</b>	GND	0x44
<b>VS</b>	VS	0x45
<b>VS</b>	SDA	0x46
<b>VS</b>	SCL	0x47
<b>SDA</b>	GND	0x48
<b>SDA</b>	VS	0x49
<b>SDA</b>	SDA	0x4A
<b>SDA</b>	SCL	0x4B
<b>SCL</b>	GND	0x4C
<b>SCL</b>	VS	0x4D
<b>SCL</b>	SDA	0x4E
<b>SCL</b>	SCL	0x4F

### Arduino wiring

- VCC/VSS → Arduino 5V (or 3.3V)
- GND → Arduino GND
- SDA → Arduino SDA (A4 on Uno)
- SCL → Arduino SCL (A5 on Uno)

### Arduino example code

In the Arduino IDE, go to *Tools > Manage Libraries*, search for “**INA226\_WE**”, and install the version by *Wollewald*.

This sketch initializes the sensor at the default address (**0x40**) and prints current, voltage, and power to the Serial Monitor.

```
#include <Wire.h>
#include <INA226_WE.h>

#define I2C_ADDRESS 0x40

INA226_WE ina226 = INA226_WE(I2C_ADDRESS);
```

```
void setup() {
  Serial.begin(9600);
  Wire.begin();

  // Initialize INA226
  if (!ina226.init()) {
    Serial.println("Failed to find INA226 chip. Check wiring!");
    while (1);
  }

  /*
   * Optional: Calibrate for your shunt.
   * Default is usually 0.1 Ohm.
   * Parameters: (Shunt value in Ohms, Max expected current in Amps)
   */
  ina226.waitUntilConversionCompleted();
  Serial.println("INA226 Ready!");
}

void loop() {
  float shuntVoltage_mV = 0.0;
  float loadVoltage_V = 0.0;
  float busVoltage_V = 0.0;
  float current_mA = 0.0;
  float power_mW = 0.0;

  // Read values
  ina226.readAndClearFlags();
  shuntVoltage_mV = ina226.getShuntVoltage_mV();
  busVoltage_V = ina226.getBusVoltage_V();
  current_mA = ina226.getCurrent_mA();
  power_mW = ina226.getBusPower_mW();
  loadVoltage_V = busVoltage_V + (shuntVoltage_mV / 1000);

  // Print results
  Serial.print("Bus Voltage: "); Serial.print(busVoltage_V);
  Serial.println(" V");
  Serial.print("Current: "); Serial.print(current_mA);
  Serial.println(" mA");
  Serial.print("Power: "); Serial.print(power_mW); Serial.println("
mW");
  Serial.println("-----");

  delay(2000);
}
```

## Sources

<https://www.ti.com/product/INA226#tech-docs> (Texas Instruments datasheet)

## I<sup>2</sup>C topics on lamaPLC

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